



Overview

- Spring-damper-mass systems (mechanical displacement storage-loss-inertia)
- *CRL* system (electric charge storage-loss-inertia)
- Central force systems



Unforced spring-mass system

- $my'' + ky = 0$
- Characteristic equation $mr^2 + k = 0, r_{1,2} = \pm i\omega, \omega = \sqrt{k/m}$

$$y(t) = Ae^{i\omega t} + Be^{-i\omega t} = a \cos(\omega t) + b \sin(\omega t)$$

```
(%i1) ode: m*'diff(y,t,2)+k*y
```

```
(%o1) m\left(\frac{d^2 y}{d t^2}\right) + k y
```

```
(%i2) sol: ode2(ode,y,t)
```

Is k positive, negative or zero? **positive**

```
(%o2) y = %k1 \sin\left(\frac{\sqrt{k} t}{\sqrt{m}}\right) + %k2 \cos\left(\frac{\sqrt{k} t}{\sqrt{m}}\right)
```

```
(%i3)
```



Unforced spring-damper-mass system

- $my'' + cy' + ky = 0$
- Characteristic equation $mr^2 + cr + k = 0$, $r_{1,2} = -\frac{c}{2m} \pm \frac{\sqrt{c^2 - 4km}}{2m}$. Cases:
 - Distinct real roots. $c^2 - 4km > 0$,

$$y(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}.$$

- Distinct imaginary roots. $c^2 - 4km < 0$,

$$y(t) = e^{-\alpha t} (c_1 \cos \beta t + c_2 \sin \beta t), \alpha = \frac{c}{2m}, \beta = \frac{\sqrt{4km - c^2}}{2m}.$$

- Repeated real roots $c^2 - 4km = 0$,

$$y(t) = c_1 e^{rt} + c_2 t e^{rt}, r = -\frac{c}{2m}.$$



Unforced spring-damper-mass system, $c^2 - 4km > 0$

Example. $y'' - 5y' + 6y = 0, y(0) = 1, y'(0) = 0, r^2 - 5r + 6 = 0 \Rightarrow r_1 = 2, r_3 = 3$

$$y(t) = c_1 e^{2t} + c_2 e^{3t}, y(0) = c_1 + c_2 = 1, y'(0) = 2c_1 + 3c_2 = 0.$$

```
(%i1) ode: 'diff(y,t,2)-5*'diff(y,t)+6*y
```

$$(\%o1) \frac{d^2 y}{dt^2} - 5 \left(\frac{dy}{dt} \right) + 6 y$$

```
(%i2) sol: ode2(ode,y,t)
```

$$(\%o2) y = \%k1 e^{3t} + \%k2 e^{2t}$$

```
(%i3) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

$$(\%o3) y = 3 e^{2t} - 2 e^{3t}$$

```
(%i4)
```



Unforced spring-damper-mass system, $c^2 - 4km < 0$

Example. $y'' + 2y' + 2y = 0, \quad y(0) = 1, \quad y'(0) = 0, \quad r^2 + 2r + 2 = 0 \Rightarrow r_{1,2} = 1 \pm i$

$$\alpha = 1, \beta = 1, \quad y(t) = e^{-\alpha t}(c_1 \cos \beta t + c_2 \sin \beta t).$$

```
(%i4) ode: 'diff(y,t,2)+2*'diff(y,t)+2*y
```

```
(%o4)  $\frac{d^2 y}{dt^2} + 2 \left( \frac{dy}{dt} \right) + 2 y$ 
```

```
(%i5) sol: ode2(ode,y,t)
```

```
(%o5)  $y = e^{-t} (\%k1 \sin(t) + \%k2 \cos(t))$ 
```

```
(%i7) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

```
(%o7)  $y = e^{-t} (\sin(t) + \cos(t))$ 
```

```
(%i8)
```



Unforced spring-damper-mass system, $c^2 - 4km = 0$

Example. $y'' + 2y' + y = 0, \quad y(0) = 1, \quad y'(0) = 0, \quad r^2 + 2r + 1 = 0 \Rightarrow r = -1$

$$y(t) = e^{-rt}(c_1 + c_2 t).$$

```
(%i8) ode: 'diff(y,t,2)+2*'diff(y,t)+y
```

```
(%o8)  $\frac{d^2 y}{dt^2} + 2 \left( \frac{dy}{dt} \right) + y$ 
```

```
(%i9) sol: ode2(ode,y,t)
```

```
(%o9)  $y = (\%k2 t + \%k1) e^{-t}$ 
```

```
(%i10) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

```
(%o10)  $y = (t + 1) e^{-t}$ 
```

```
(%i11)
```



Forced spring-mass system - non-resonant forcing

- $my'' + ky = f(t)$, $mr^2 + k = 0$, $r_{1,2} = \pm i\omega$, $\omega = \sqrt{k/m}$
- Non-resonant forcing: $f(t)$ not proportional to $\cos(\omega t)$, $\sin(\omega t)$
- Steps:
 - 1 Solve homogeneous equation $y_h = a \cos(\omega t) + b \sin(\omega t)$
 - 2 Search for a particular solution suggested by force term

```
(%i14) ode: 'diff(y,t,2)+4*y-t
```

```
(%o14)  $\frac{d^2 y}{dt^2} + 4 y - t$ 
```

```
(%i15) sol: ode2(ode,y,t)
```

```
(%o15)  $y = \%k1 \sin(2t) + \%k2 \cos(2t) + \frac{t}{4}$ 
```

(%i16) `ic2(sol,t=0,y=1,'diff(y,t)=0)`

$$(\%o16) \quad y = -\frac{\sin(2t)}{8} + \cos(2t) + \frac{t}{4}$$

(%i17)



Forced mass-spring system, resonant forcing

- $my'' + ky = f(t)$, $mr^2 + k = 0$, $r_{1,2} = \pm i\omega$, $\omega = \sqrt{k/m}$
- Non-resonant forcing: $f(t)$ proportional to $\cos(\omega t)$, $\sin(\omega t)$
- Steps:
 - 1 Solve homogeneous equation $y_h = a \cos(\omega t) + b \sin(\omega t)$
 - 2 Search for a particular solution of form $t(A \cos \omega t + B \sin \omega t)$

```
(%i17) ode: 'diff(y,t,2)+4*y-sin(2*t)
```

```
(%o17)  $\frac{d^2 y}{dt^2} + 4 y - \sin(2t)$ 
```

```
(%i18) sol: ode2(ode,y,t)
```

```
(%o18)  $y = \%k1 \sin(2t) - \frac{t \cos(2t)}{4} + \%k2 \cos(2t)$ 
```

(%i13) `ic2(sol,t=0,y=1,'diff(y,t)=0)`

(%o13) $y = -\frac{17 e^{3t}}{9} + \frac{11 e^{2t}}{4} + \frac{5 + 6t}{36}$

(%i14)



Example. $y'' - 5y' + 6y = \sin t$, $r^2 - 5r + 6 = 0 \Rightarrow r_1 = 2, r_3 = 3$

$$y_h(t) = c_1 e^{2t} + c_2 e^{3t}, y_p = A \sin t + B \cos t.$$

```
(%i19) ode: 'diff(y,t,2)-5*'diff(y,t)+6*y - sin(t)
```

$$(\%o19) \frac{d^2 y}{dt^2} - 5 \left(\frac{dy}{dt} \right) + 6 y - \sin(t)$$

```
(%i20) sol: ode2(ode,y,t)
```

$$(\%o20) y = \frac{\cos(t) + \sin(t)}{10} + \%k1 e^{3t} + \%k2 e^{2t}$$

```
(%i21) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

$$(\%o21) y = \frac{\cos(t) + \sin(t)}{10} - \frac{19 e^{3t}}{10} + \frac{14 e^{2t}}{5}$$

```
(%i22)
```



Forced spring-damper-mass system $c^2 - 4km > 0$, resonant

Example. $y'' - 5y' + 6y = e^{2t}$, $r^2 - 5r + 6 = 0 \Rightarrow r_1 = 2, r_3 = 3$

$$y_h(t) = c_1 e^{2t} + c_2 e^{3t}, y_p = A e^{2t} + B t e^{2t}.$$

```
(%i22) ode: 'diff(y,t,2)-5*'diff(y,t)+6*y - exp(2*t)
```

```
(%o22)  $\frac{d^2 y}{dt^2} - 5 \left( \frac{dy}{dt} \right) + 6 y - e^{2t}$ 
```

```
(%i23) sol: ode2(ode,y,t)
```

```
(%o23)  $y = \%k1 e^{3t} + (-1 - t) e^{2t} + \%k2 e^{2t}$ 
```

```
(%i24) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

```
(%o24)  $y = -e^{3t} + (-1 - t) e^{2t} + 3 e^{2t}$ 
```

```
(%i25)
```



Forced spring-damper-mass system, $c^2 - 4km < 0$, non-resonant

Example. $y'' + 2y' + 2y = t$, $r^2 + 2r + 2 = 0 \Rightarrow r_{1,2} = 1 \pm i$

$$\alpha = 1, \beta = 1, y_h(t) = e^{-\alpha t}(c_1 \cos \beta t + c_2 \sin \beta t), y_p = A + Bt$$

```
(%i25) ode: 'diff(y,t,2)+2*'diff(y,t)+2*y -t
```

$$(\%o25) \frac{d^2 y}{dt^2} + 2 \left(\frac{dy}{dt} \right) + 2 y - t$$

```
(%i26) sol: ode2(ode,y,t)
```

$$(\%o26) y = e^{-t} (\%k2 \cos(t) + \%k1 \sin(t)) + \frac{t-1}{2}$$

```
(%i27) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

$$(\%o27) y = e^{-t} \left(\frac{3 \cos(t)}{2} + \sin(t) \right) + \frac{t-1}{2}$$

```
(%i28)
```



Forced spring-damper-mass system, $c^2 - 4km < 0$, resonant

Example. $y'' + 2y' + 2y = e^{-t} \sin t$, $r^2 + 2r + 2 = 0 \Rightarrow r_{1,2} = 1 \pm i$

$\alpha = 1$, $\beta = 1$, $y_h(t) = e^{-\alpha t}(c_1 \cos \beta t + c_2 \sin \beta t)$, $y_p = te^{-t}(A \cos t + B \sin t)$

```
(%i31) ode: 'diff(y,t,2)+2*'diff(y,t)+2*y - exp(-t)*sin(t)
```

$$(\%o31) \frac{d^2 y}{dt^2} + 2 \left(\frac{dy}{dt} \right) + 2 y - e^{-t} \sin(t)$$

```
(%i32) sol: ode2(ode,y,t)
```

$$(\%o32) y = e^{-t} (\%k2 \cos(t) + \%k1 \sin(t)) - \frac{t e^{-t} \cos(t)}{2}$$

```
(%i39) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

$$(\%o39) y = e^{-t} \left(\cos(t) + \frac{3 \sin(t)}{2} \right) - \frac{t e^{-t} \cos(t)}{2}$$

(%i40)



Forced spring-damper-mass system, $c^2 - 4km = 0$, non-resonant

Example. $y'' + 2y' + y = t$, $r^2 + 2r + 1 = 0 \Rightarrow r = -1$

$$y_h(t) = e^{-rt}(c_1 + c_2 t), y_p = A + Bt$$

```
(%i40) ode: 'diff(y,t,2)+2*'diff(y,t)+y - t
```

$$(\%o40) \frac{d^2 y}{dt^2} + 2 \left(\frac{dy}{dt} \right) + y - t$$

```
(%i41) sol: ode2(ode,y,t)
```

$$(\%o41) y = (\%k1 + \%k2 t) e^{-t} + t - 2$$

```
(%i42) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

$$(\%o42) y = (3 + 2t) e^{-t} + t - 2$$

```
(%i43)
```



Forced spring-damper-mass system, $c^2 - 4km = 0$, resonant

Example. $y'' + 2y' + y = te^{-t}$, $r^2 + 2r + 1 = 0 \Rightarrow r = -1$

$$y_h(t) = e^{-rt}(c_1 + c_2 t), y_p = (A + Bt)t^2 e^{-rt}$$

```
(%i43) ode: 'diff(y,t,2)+2*'diff(y,t)+y - t*exp(-t)
```

$$(\%o43) \frac{d^2 y}{dt^2} + 2 \left(\frac{dy}{dt} \right) + y - t e^{-t}$$

```
(%i44) sol: ode2(ode,y,t)
```

$$(\%o44) y = \frac{t^3 e^{-t}}{6} + (\%k1 + \%k2 t) e^{-t}$$

```
(%i45) ic2(sol,t=0,y=1,'diff(y,t)=0)
```

$$(\%o45) y = \frac{t^3 e^{-t}}{6} + (1 + t) e^{-t}$$

```
(%i46)
```