

HOMEWORK 6 SOLUTION

Due date: Feb 20, 2020, 11:55PM.

Bibliography: Lesson09.pdf Lesson10.pdf. The first exercise in each problem set is solved for you to use as a model.

1. Consider $\mathcal{V} = \mathbb{R}^n$, $\mathcal{S} = \mathbb{R}$. Determine whether the column vectors of $\mathbf{A}$ form a basis for $\mathbb{R}^n$.

Ex 1. $n = 3$,

$$\mathbf{A} = \begin{pmatrix} -1 & 1 & 1 \\ 2 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}.$$

Solution. Reduce $\mathbf{A}$ to row-echelon form

$$\mathbf{A} \sim \begin{pmatrix} -1 & 1 & 1 \\ 0 & 2 & 3 \\ 0 & 2 & 2 \end{pmatrix} \sim \begin{pmatrix} -1 & 1 & 1 \\ 0 & 2 & 3 \\ 0 & 0 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & -1 & -1 \\ 0 & 1 & \frac{3}{2} \\ 0 & 0 & 1 \end{pmatrix}$$

Since the row-echelon form does not contain a row of zeros, the columns of $\mathbf{A}$ form a basis for $\mathbb{R}^3$. Check in Maxima

```
(%i1) A: matrix([-1, 1, 1],[2, 0, 1],[1, 1, 1]);
```

```
(%o1)  $\begin{pmatrix} -1 & 1 & 1 \\ 2 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ 
```

```
(%i2) echelon(A);
```

```
(%o2)  $\begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & \frac{3}{2} \\ 0 & 0 & 1 \end{pmatrix}$ 
```

```
(%i3)
```

Note: multiple row-echelon forms are possible (differing by, say, permutation of rows), but the same conclusion on the independence is reached, i.e., no zero rows implies linear independence.

Ex 2. $n = 3$,

$$\mathbf{A} = \begin{pmatrix} 2 & 5 & 3 \\ -2 & 1 & 1 \\ 1 & 2 & 1 \end{pmatrix}.$$

Solution. Reduce $\mathbf{A}$ to row-echelon form

$$\mathbf{A} \sim \begin{pmatrix} 2 & 5 & 3 \\ 0 & 6 & 4 \\ 0 & -1 & -1 \end{pmatrix} \sim \begin{pmatrix} 2 & 5 & 3 \\ 0 & 3 & 2 \\ 0 & 0 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & \frac{5}{2} & \frac{3}{2} \\ 0 & 1 & \frac{2}{3} \\ 0 & 0 & 1 \end{pmatrix}$$

Since the row-echelon form does not contain a row of zeros, the columns of $\mathbf{A}$ form a basis for $\mathbb{R}^3$. Check in Maxima

```
(%i39) A: matrix([2, 5, 3],[-2, 1, 1],[1, 2, 1]);
```

$$(\%o39) \begin{pmatrix} 2 & 5 & 3 \\ -2 & 1 & 1 \\ 1 & 2 & 1 \end{pmatrix}$$

(%i40) echelon(A);

$$(\%o40) \begin{pmatrix} 1 & \frac{5}{2} & \frac{3}{2} \\ 0 & 1 & \frac{2}{3} \\ 0 & 0 & 1 \end{pmatrix}$$

(%i41)

Ex 3. $n=4$,

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 2 & -1 \\ 1 & 1 & 4 & 2 \\ -1 & 3 & 2 & 0 \\ 1 & 1 & 5 & 3 \end{pmatrix}.$$

Solution. Reduce $\mathbf{A}$ to row-echelon form

$$\mathbf{A} \sim \begin{pmatrix} 1 & 2 & 2 & -1 \\ 0 & -1 & 2 & 3 \\ 0 & 5 & 4 & -1 \\ 0 & -1 & 3 & 4 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 2 & -1 \\ 0 & 1 & -2 & -3 \\ 0 & 0 & 14 & 14 \\ 0 & 0 & 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 2 & -1 \\ 0 & 1 & -2 & -3 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

The row-echelon form does contain a row of zeros, the columns of $\mathbf{A}$ do not form a basis for $\mathbb{R}^4$. Check in Maxima

(%i41) A: matrix([1, 2, 2, -1],[1, 1, 4, 2],[-1, 3, 2, 0],[1, 1, 5, 3]);

$$(\%o41) \begin{pmatrix} 1 & 2 & 2 & -1 \\ 1 & 1 & 4 & 2 \\ -1 & 3 & 2 & 0 \\ 1 & 1 & 5 & 3 \end{pmatrix}$$

(%i42) echelon(A);

$$(\%o42) \begin{pmatrix} 1 & -3 & -2 & 0 \\ 0 & 1 & \frac{3}{2} & \frac{1}{2} \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

(%i43)

Ex 4. $n=4$,

$$\mathbf{A} = \begin{pmatrix} -1 & 2 & 1 & 2 \\ 1 & 1 & 3 & 1 \\ 0 & -1 & 1 & 1 \\ 1 & 2 & -1 & 2 \end{pmatrix}.$$

Solution. Having understood the procedure of using row operations to obtain the reduced row-echelon form, resort not to automated computation and obtain in Maxima

(%i43) A: matrix([-1, 2, 1, 2],[1, 1, 3, 1],[0, -1, 1, 1],[1, 2, -1, 2]);

$$(\%o43) \begin{pmatrix} -1 & 2 & 1 & 2 \\ 1 & 1 & 3 & 1 \\ 0 & -1 & 1 & 1 \\ 1 & 2 & -1 & 2 \end{pmatrix}$$

(%i44) echelon(A);

(%o44)
$$\begin{pmatrix} 1 & -2 & -1 & -2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

(%i45)

The row-echelon form does not contain any row of zeros, the columns of $\mathbf{A}$ form a basis for $\mathbb{R}^4$.

2. Determine whether the following column vectors of $\mathbf{B}$ form a basis for $(\mathcal{V}, +, \mathbb{R}, \cdot)$

Ex 1. $\mathbf{B} = \begin{pmatrix} 1 & 2x^2 + x + 2 & -x^2 + x \end{pmatrix}$, $\mathcal{V} = \mathcal{P}_2$

Solution. Consider an arbitrary $\mathbf{p} \in \mathcal{V} = \mathcal{P}_2$

$$\mathbf{p}(x) = a_0 + a_1x + a_2x^2,$$

and check if $\mathbf{p}$ can be expressed as a linear combination of the basis vectors, $\mathbf{B}$, i.e., there exists $\mathbf{c} \in \mathbb{R}^3$ such that $\mathbf{B}\mathbf{c} = \mathbf{p}$

$$\mathbf{B}\mathbf{c} = \begin{pmatrix} \mathbf{b}_1(x) & \mathbf{b}_2(x) & \mathbf{b}_3(x) \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = c_1\mathbf{b}_1(x) + c_2\mathbf{b}_2(x) + c_3\mathbf{b}_3(x) = a_0 + a_1x + a_2x^2 = \mathbf{p}(x).$$

Identify powers of x

$$c_1\mathbf{b}_1(x) + c_2\mathbf{b}_2(x) + c_3\mathbf{b}_3(x) = c_1 + c_2(2x^2 + x + 2) + c_3(-x^2 + x) = (c_1 + 2c_2) \cdot 1 + (c_1 + c_2) \cdot x + (2c_2 - c_3) \cdot x^2$$

to obtain system $\mathbf{M}\mathbf{c} = \mathbf{a}$

$$\begin{pmatrix} 1 & 2 & 0 \\ 1 & 1 & 0 \\ 0 & 2 & -1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} a_0 \\ a_1 \\ a_2 \end{pmatrix},$$

Reduce matrix $\mathbf{M}$ to row-echelon form.

$$\mathbf{M} = \begin{pmatrix} 1 & 2 & 0 \\ 1 & 1 & 0 \\ 0 & 2 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 0 \\ 0 & -1 & 0 \\ 0 & 2 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Since the row-echelon form of $\mathbf{M}$ does not have any zero rows, a unique solution of $\mathbf{M}\mathbf{c} = \mathbf{a}$ is found, and $\mathbf{B}$ is a basis for $\mathcal{P}_3$. Check in Maxima

(%i3) M: matrix([1, 2, 0],[1, 1, 0],[0, 2, -1]);

(%o3)
$$\begin{pmatrix} 1 & 2 & 0 \\ 1 & 1 & 0 \\ 0 & 2 & -1 \end{pmatrix}$$

(%i4) echelon(M);

(%o4)
$$\begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

(%i5)

Ex 2. $\mathcal{V} = \mathbb{R}^{2 \times 2}$ the space of real-valued two-by-two matrices,

$$\mathbf{B} = \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} -2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 2 \end{pmatrix} \right)$$

Solution. Here are two approaches:

1. The basis can be reorganized as a set of $\mathbb{R}^4$ vectors

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \text{etc.}; \mathbf{B} = \begin{pmatrix} 1 & 1 & -2 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

Reduce $\mathbf{B}$ to row echelon form

```
(%i45) B: matrix([1, 1, -2, 0],[0, 0, 1, 0],[0, 1, 1, 0],[0, 0, 1, 2]);
```

```
(%o45) 
$$\begin{pmatrix} 1 & 1 & -2 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

```

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(%i47) echelon(B);
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(%o47) 
$$\begin{pmatrix} 1 & 1 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

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(%i48)
```

Since the reduced row echelon form has no row of zeros $\mathbf{B}$ is a basis

2. Denote $\mathbf{B} = (\mathbf{B}_1, \mathbf{B}_2, \mathbf{B}_3, \mathbf{B}_4)$, and consider whether some general

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \in \mathbb{R}^{2 \times 2}$$

can be expressed as a linear combination $\mathbf{A} = c_1 \mathbf{B}_1 + c_2 \mathbf{B}_2 + c_3 \mathbf{B}_3 + c_4 \mathbf{B}_4$

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = c_1 \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + c_2 \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} + c_3 \begin{pmatrix} -2 & 1 \\ 1 & 1 \end{pmatrix} + c_4 \begin{pmatrix} 0 & 0 \\ 0 & 2 \end{pmatrix}.$$

Identify each component to obtain the system

$$\begin{cases} c_1 + c_2 - 2c_3 & = & a_{11} \\ c_2 + c_3 & = & a_{12} \\ c_3 & = & a_{21} \\ c_3 + 2c_4 & = & a_{22} \end{cases} \Rightarrow \begin{pmatrix} 1 & 1 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{pmatrix} = \begin{pmatrix} a_{11} \\ a_{12} \\ a_{21} \\ a_{22} \end{pmatrix}.$$

Apart from a permutation of two rows, this is the same as matrix in solution procedure 1, and $\mathbf{B}$ does form a basis

Ex 3. $\mathcal{V}$ is the set of symmetric matrices, $\mathbf{A} \in \mathcal{V} \Rightarrow \mathbf{A}^T = \mathbf{A}$.

$$\mathbf{B} = \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right)$$

Solution. Since

$$\mathbf{A} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

cannot be expressed as a linear combination of elements in $\mathbf{B}$, the system is not a basis. This is verified if we form the matrix

$$\mathbf{B} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

which has a row of zeros.

3. Find a basis for the subspace $\mathcal{S}$ of vector space $\mathcal{V}$. Specify the dimension of $\mathcal{S}$.

Ex 1.

$$\mathcal{S} = \left\{ \begin{pmatrix} s+2t \\ -s+t \\ t \end{pmatrix} \mid s, t \in \mathbb{R} \right\}, \mathcal{V} = \mathbb{R}^3$$

Solution. Recognize that the specification of $\mathcal{S}$ gives a linear combination with scalar coefficients s, t , and rewrite

$$\begin{pmatrix} s+2t \\ -s+t \\ t \end{pmatrix} = s \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}.$$

Construct

$$\mathbf{B} = (\mathbf{b}_1 \ \mathbf{b}_2) = \begin{pmatrix} 1 & 2 \\ -1 & 1 \\ 0 & 1 \end{pmatrix}.$$

Check if columns of $\mathbf{B}$ are linearly independent,

$$s\mathbf{b}_1 + t\mathbf{b}_2 = \mathbf{0} \Rightarrow \begin{pmatrix} s+2t \\ -s+t \\ t \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix},$$

and since $s=t=0$ is the only solution, columns of $\mathbf{B}$ are linearly independent and span the subspace, hence are a basis for $\mathcal{S}$.

Ex 2.

$$\mathcal{S} = \left\{ \begin{pmatrix} a & a+d \\ a+d & d \end{pmatrix} \mid a, d \in \mathbb{R} \right\}, \mathcal{V} = \mathbb{R}^{2 \times 2}$$

Solution. Since

$$\begin{pmatrix} a & a+d \\ a+d & d \end{pmatrix} = a \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} + d \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\mathbf{B} = \left(\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \ \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} \right)$$

is a basis.

Ex 3. $\mathcal{S}$ is the space of skew-symmetric matrices ($\mathbf{A} \in \mathcal{S} \Rightarrow \mathbf{A}^T = -\mathbf{A}$), $\mathcal{V} = \mathbb{R}^{2 \times 2}$ Solution. Since

$$\begin{pmatrix} 0 & a \\ -a & 0 \end{pmatrix} = a \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$\mathbf{B} = \left(\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right)$$

is a basis.

Ex 4. $\mathcal{S} = \{p(x) \mid p(0) = 0\}$, $\mathcal{V} = \mathcal{P}_2$.

Solution. Since $\mathbf{p} \in \mathcal{S} \Rightarrow \mathbf{p} = ax^2 + bx$, $\mathbf{B} = \{x, x^2\}$ is a basis.

Ex 5. $\mathcal{S} = \{p(x) \mid p(0) = 0, p(1) = 0\}$, $\mathcal{V} = \mathcal{P}_3$.

Solution. Since $\mathbf{p} \in \mathcal{S} \Rightarrow \mathbf{p} = ax^3 + bx^2 + cx$, with $\mathbf{p}(1) = a + b + c = 0 \Rightarrow c = -(a + b)$, hence

$$\mathbf{p} = ax^3 + bx^2 - (a + b)x = a(x^3 - x) + b(x^2 - x),$$

such that $\mathbf{B} = \{x^3 - x, x^2 - x\}$ is a basis.

4. Find the coordinates of the vector $\mathbf{v}$ in the basis $\mathbf{B}$.

Ex 1.

$$\mathbf{B} = \begin{pmatrix} 3 & -2 \\ 1 & 2 \end{pmatrix}, \mathbf{v} = \begin{pmatrix} 8 \\ 0 \end{pmatrix}, \mathcal{V} = \mathbb{R}^2$$

Solution. If $\mathbf{B}$ is a basis for $\mathcal{V} = \mathbb{R}^2$, then the vector $\mathbf{v}$ can be expressed as a linear combination of the basis vectors and that scalar coefficients are the coordinates of $\mathbf{v}$ in basis $\mathbf{B}$

$$\mathbf{v} = x_1 \mathbf{b}_1 + x_2 \mathbf{b}_2 = \mathbf{B} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \text{Solve} \begin{pmatrix} 3 & -2 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 8 \\ 0 \end{pmatrix}$$

to find the coordinates $x_1 = 2, x_2 = -1$. Check in Maxima.

```
(%i5) B:matrix([3,-2],[1,2]);
```

```
(%o5)  $\begin{pmatrix} 3 & -2 \\ 1 & 2 \end{pmatrix}$ 
```

```
(%i6) v:matrix([8],[0]);
```

```
(%o6)  $\begin{pmatrix} 8 \\ 0 \end{pmatrix}$ 
```

```
(%i7) linsolve_by_lu(B,v);
```

0 errors, 0 warnings

```
(%o7)  $\left[ \begin{pmatrix} 2 \\ -1 \end{pmatrix}, \text{false} \right]$ 
```

```
(%i8) x: first(%);
```

```
(%o8)  $\begin{pmatrix} 2 \\ -1 \end{pmatrix}$ 
```

```
(%i9) B.x
```

```
(%o9)  $\begin{pmatrix} 8 \\ 0 \end{pmatrix}$ 
```

```
(%i10)
```

Ex 2.

$$\mathbf{B} = \begin{pmatrix} -2 & -1 \\ 4 & 1 \end{pmatrix}, \mathbf{v} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}, \mathcal{V} = \mathbb{R}^2$$

Solution. Solve by Gauss elimination (row reduction operations on the extended matrix)

$$\begin{pmatrix} -2 & -1 & -2 \\ 4 & 1 & 1 \end{pmatrix} \sim \begin{pmatrix} -2 & -1 & -2 \\ 0 & -1 & -3 \end{pmatrix} \sim \begin{pmatrix} -2 & 0 & 1 \\ 0 & 1 & 3 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -\frac{1}{2} \\ 0 & 1 & 3 \end{pmatrix}$$

and the coordinates are $(-\frac{1}{2}, 3)$. Check in Maxima

```
(%i48) B:matrix([-2,-1],[4,1]);
```

```
(%o48)  $\begin{pmatrix} -2 & -1 \\ 4 & 1 \end{pmatrix}$ 
(%i49) v:matrix([-2],[1]);
(%o49)  $\begin{pmatrix} -2 \\ 1 \end{pmatrix}$ 
(%i50) linsolve_by_lu(B,v);
```

0 errors, 0 warnings

```
(%o50)  $\left[ \begin{pmatrix} -\frac{1}{2} \\ 3 \end{pmatrix}, \text{false} \right]$ 
```

Ex 3.

$$\mathbf{B} = \begin{pmatrix} 1 & 3 & 1 \\ -1 & -1 & 0 \\ 2 & 1 & 2 \end{pmatrix}, \mathbf{v} = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, \mathcal{V} = \mathbb{R}^3$$

Solution. Since $\mathbf{B} = (\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3)$, and $\mathbf{v} = \mathbf{b}_3$ the coordinates are $(0, 0, 1)$.

Ex 4.

$$\mathbf{B} = \begin{pmatrix} 2 & 1 & 0 \\ 2 & 0 & 0 \\ 1 & 2 & 1 \end{pmatrix}, \mathbf{v} = \begin{pmatrix} 0 \\ 1 \\ \frac{1}{2} \end{pmatrix}, \mathcal{V} = \mathbb{R}^3$$

Solution. With $\mathbf{B} = (\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3)$, from

$$\mathbf{v} = c_1 \mathbf{b}_1 + c_2 \mathbf{b}_2 + c_3 \mathbf{b}_3$$

observe from second row that $c_1 = \frac{1}{2}$. Then

$$\frac{1}{2} \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} + c_3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 + c_2 \\ 1 \\ \frac{1}{2} + 2c_2 + c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ \frac{1}{2} \end{pmatrix}$$

and the other coordinates are $c_2 = -1$, $c_3 = 2$. Verify in Maxima

```
(%i51) B:matrix([2,1,0],[2,0,0],[1,2,1]);
```

```
(%o51)  $\begin{pmatrix} 2 & 1 & 0 \\ 2 & 0 & 0 \\ 1 & 2 & 1 \end{pmatrix}$ 
```

```
(%i52) v:matrix([0],[1],[1/2]);
```

```
(%o52)  $\begin{pmatrix} 0 \\ 1 \\ \frac{1}{2} \end{pmatrix}$ 
```

```
(%i53) linsolve_by_lu(B,v);
```

```
(%o53)  $\left[ \begin{pmatrix} \frac{1}{2} \\ -1 \\ 2 \end{pmatrix}, \text{false} \right]$ 
```

```
(%i54)
```

Ex 5.

$$\mathbf{B} = \begin{pmatrix} 1 & x-1 & x^2 \end{pmatrix}, \mathbf{v} = -2x^2 + 2x + 3, \mathcal{V} = \mathcal{P}_2$$

Solution. With $\mathbf{B} = (\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3)$ write

$$\mathbf{v} = -2\mathbf{b}_3 + 2\mathbf{b}_2 + 5\mathbf{b}_1 = -2(x^2) + 2(x-1) + 5(1) = -2x^2 + 2x - 2 + 5 = -2x^2 + 2x + 3,$$

and the coordinates are $(5, 2, -2)$.