

Remark. Many mathematical techniques involve *linear combinations*

- in linear algebra, $\alpha \mathbf{u} + \beta \mathbf{v}$, $\alpha, \beta \in \mathbb{C}$ scalars, $\mathbf{u}, \mathbf{v} \in \mathbb{C}^n$, vectors
- in calculus, $d(\alpha f + \beta g) = \alpha df + \beta dg$, $\alpha, \beta \in \mathbb{R}$ scalars, $f, g: \mathbb{R} \rightarrow \mathbb{R}$, functions

Definition. A first-order ODE of form $y' + p(x)y = r(x)$ is said to be *linear*.

Definition. A first-order ODE of form $y' + p(x)y = 0$ is said to be *homogeneous linear*.

Remark. A first-order homogeneous linear ODE is separable with solution

$$\frac{dy}{y} = -p dx \Rightarrow \ln y = - \int p(x) dx + \ln c \Rightarrow y = ce^{-\int p(x) dx}$$

Remark. A first-order non-homogeneous linear ODE leads to a differential form

$$(p(x)y - r(x)) dx + dy = 0, P(x, y) = p(x)y - r(x), Q(x, y) = 1,$$

for which

$$\frac{1}{Q(x, y)} \left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right) = p(x),$$

such that

$$F(x) = \exp \int p(x) dx = \exp h,$$

is an integrating factor with property $F' = pF$ such that the linear ODE can be rewritten in separable form

$$Fy' + Fpy = Fy' + F' y = \frac{d}{dx}(Fy) = r$$

Corollary. (of Theorem 1, Lesson 2) The solution to $y' + p(x)y = r(x)$ is

$$y(x) = e^{-h(x)} \left(\int e^{h(x)} r(x) dx + c \right), h(x) = \int p(x) dx$$

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In[10]:= DSolve[y'[x] + p[x] y[x] == r[x], y[x], x]
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$$\left\{ \left\{ y(x) \rightarrow c_1 e^{\int_1^x -p(K[1]) dK[1]} + e^{\int_1^x -p(K[1]) dK[1]} \int_1^x r(K[2]) e^{-\int_1^{K[2]} -p(K[1]) dK[1]} dK[2] \right\} \right\}$$

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In[11]:= h[x_] = Integrate[p[x], x]
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$$\int p(x) dx$$

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In[13]:= y[x_] = Exp[-h[x]] ( Integrate[ Exp[h[x]] r[x], x ] + c)
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$$e^{-\int p(x) dx} \left(c + \int r(x) e^{\int p(x) dx} dx \right)$$

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In[14]:= linODE = y'[x] + p[x] y[x] == r[x]
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True

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In[15]:=
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Example 1. $y' + y \tan x = \sin 2x, y(0) = 1.$

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In[15]:= y[x]
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$$e^{-\int p(x) dx} \left(c + \int r(x) e^{\int p(x) dx} dx \right)$$

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In[19]:= sol[x_]=y[x] /. {p[x]->Tan[x], r[x]->Sin[2x]}
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$$\cos(x) (c - 2 \cos(x))$$

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In[21]:= Simplify[sol'[x] + sol[x] Tan[x] == Sin[2x]]
```

True

```
In[23]:= Simplify[DSolve[z'[x] + Tan[x] z[x] == Sin[2x], z[x], x]]
```

$$\{\{z(x) \rightarrow \cos(x) (c_1 - 2 \cos(x))\}\}$$

```
In[24]:=
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Element	Electrical	Mechanical
Independent variable	time t	time t
Dependent variable	charge $q(t)$	position $x(t)$
Rate of change of dependent variable	current $i = q'(t)$	velocity $v(t) = x'(t)$
Inertia	inductance L	mass m
Dissipation	resistor R	drag b
Storage	capacitance C	spring k
Forcing	external voltage $u(t)$	external force $f(t)$
Inertia-dissipation model	$Li' + Ri = u$	$mv' + bv = f$

```
In[36]:= sol[t_] = Apart[i[t] /. DSolve[ {L i'[t] + R i[t] == u, i[0]==j}, i[t], t][[1,1]];
plt = Plot[ Table[sol[t] /. {R->12, L->0.1, u->48}, {j,0,8,2}],{t,0,0.05},PlotRange->All];
Export["/home/student/courses/MATH528/L03Fig01.pdf",plt]; sol[t]
```

$$\frac{(jR - u)e^{-\frac{Rt}{L}}}{R} + \frac{u}{R}$$

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In[37]:=
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Figure 1. Inertia-dissipation model returns to steady-state after initial perturbation

Definition. A non-linear first-order ODE of form $y' + p(x)y = g(x) y^a$ is said to be a *Bernoulli equation*.

Remark. A Bernoulli equation can be brought to linear form through the substitution $u(x) = [y(x)]^{1-a}$

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In[34]:= Clear[y]; BernoulliEq = y'[x] + p[x] y[x] == g[x] y[x]^a
```

$$p(x) y(x) + y'(x) = g(x) y(x)^a$$

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In[32]:= y[x_] = u[x]^(1/(1-a))
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$$u(x)^{\frac{1}{1-a}}$$

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In[33]:= TransformedEq = FullSimplify[BernoulliEq]
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$$\frac{u(x)^{-\frac{a}{a-1}} ((a-1) p(x) u(x) - u'(x))}{a-1} = g(x) \left(u(x)^{\frac{1}{1-a}} \right)^a$$

Example. Logistic equation $y' = ay - by^2$, $u = y^{1-a} = y^{-1}$, $u' + au = b$