

The following model describes response of a system with inertia, dissipation, storage under excitation

$$m y'' + c y' + k y = r(t),$$

especially with $r(t) = F \cos(\omega t)$ (periodic forcing).

```
In[6] := rhs = m y''[t] + c y'[t] + k y[t]; r[t_] = F Cos[omega t];
hODE = rhs == 0;
hsol[t_,m_,c_,k_] = y[t] /. DSolve[hODE,y[t],t][[1,1]]
```

$$c_1 e^{\frac{1}{2}t \left(-\frac{\sqrt{c^2 - 4km}}{m} - \frac{c}{m} \right)} + c_2 e^{\frac{1}{2}t \left(\frac{\sqrt{c^2 - 4km}}{m} - \frac{c}{m} \right)}$$

```
In[2] := psol[t_] = a Cos[omega t] + b Sin[omega t]
```

$$a \cos(\omega t) + b \sin(\omega t)$$

```
In[3] := uCoef = Simplify[Evaluate[rhs /. y->psol] - r[t]]
```

$$\cos(\omega t) (a k - a m \omega^2 + b c \omega - F) + \sin(\omega t) (b (k - m \omega^2) - a c \omega)$$

```
In[4] := sys = {Coefficient[uCoef,Cos[omega t],1],Coefficient[uCoef,Sin[omega t],1]}=={0,0}
```

$$\{a k - a m \omega^2 + b c \omega - F, b (k - m \omega^2) - a c \omega\} = \{0, 0\}$$

```
In[5] := yp[t_,m_,c_,k_] = psol[t] /. Solve[sys,{a,b}][[1]]
```

$$\frac{c F \omega \sin(\omega t)}{c^2 \omega^2 + k^2 - 2 k m \omega^2 + m^2 \omega^4} + \frac{F (k - m \omega^2) \cos(\omega t)}{c^2 \omega^2 + k^2 - 2 k m \omega^2 + m^2 \omega^4}$$

```
In[6] :=
```

- $y(t) = y_h(t) + y_p(t)$

In[7] := `y[t_,m_,c_,k_] = hsol[t,m,c,k] + yp[t,m,c,k]`

$$\frac{c F \omega \sin(\omega t)}{c^2 \omega^2 + k^2 - 2 k m \omega^2 + m^2 \omega^4} + \frac{F (k - m \omega^2) \cos(\omega t)}{c^2 \omega^2 + k^2 - 2 k m \omega^2 + m^2 \omega^4} + c_1 e^{\frac{1}{2} t \left(-\frac{\sqrt{c^2 - 4 k m}}{m} - \frac{c}{m} \right)} + c_2 e^{\frac{1}{2} t \left(\frac{\sqrt{c^2 - 4 k m}}{m} - \frac{c}{m} \right)}$$

In[8] :=

- Undamped forced oscillations

In[14] := `yNoDamp[t_] = Assuming[m>0, Simplify[y[t,m,0,m (Subscript[omega,0])^2] /. F->(f m)]]`

$$c_1 e^{\sqrt{-\omega_0^2}(-t)} + c_2 e^{\sqrt{-\omega_0^2}t} - \frac{f \cos(\omega t)}{\omega^2 - \omega_0^2}$$

In[15] :=

(See Lesson07.nb for examples)