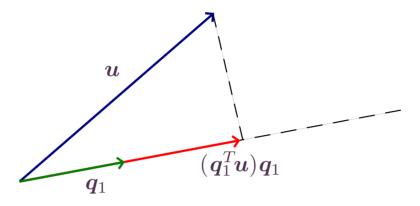
- New concepts:
 - Projector matrix, complementary projector
 - Orthogonal projection

• Consider a vector $oldsymbol{u} \in \mathbb{R}^m$, and a unit-norm vector $oldsymbol{q}_1 \in \mathbb{R}^m$

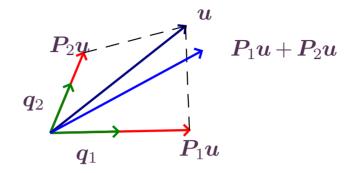


Definition. The orthogonal projection of $u \in \mathbb{R}^m$ along direction $q_1 \in \mathbb{R}^m$, $||q_1|| = 1$ is the vector $(q_1^T u)q_1$.

- Scalar-vector multiplication commutativity: $(\boldsymbol{q}_1^T \boldsymbol{u}) \boldsymbol{q}_1 = \boldsymbol{q}_1(\boldsymbol{q}_1^T \boldsymbol{u})$
- Matrix multiplication associativity: $q_1(q_1^T u) = (q_1 q_1^T) u = P_1 u$, with $P_1 \in \mathbb{R}^{m \times m}$

Definition. The matrix $P_1 = q_1 q_1^T \in \mathbb{R}^{m \times m}$ is the orthogonal projector along direction $q_1 \in \mathbb{R}^m$, $||q_1|| = 1$.

• Consider n orthonormal vectors grouped into a matrix $oldsymbol{Q} = (oldsymbol{q}_1 \ \dots \ oldsymbol{q}_n) \in \mathbb{R}^{m imes n}$



• The orthogonal projection of $oldsymbol{u}$ onto the subspace spanned by $oldsymbol{q}_1,...,oldsymbol{q}_n$ is

$$\boldsymbol{P}\boldsymbol{u} = \boldsymbol{P}_1\boldsymbol{u} + \ldots + \boldsymbol{P}_n\boldsymbol{u} = (\boldsymbol{q}_1\boldsymbol{q}_1^T)\boldsymbol{u} + \ldots + (\boldsymbol{q}_n\boldsymbol{q}_n^T)\boldsymbol{u} \Rightarrow$$

$$\boldsymbol{P} = \boldsymbol{q}_1 \boldsymbol{q}_1^T + \ldots + \boldsymbol{q}_n \boldsymbol{q}_n^T = (\boldsymbol{q}_1 \ \ldots \ \boldsymbol{q}_n) \begin{pmatrix} \boldsymbol{q}_1^T \\ \vdots \\ \boldsymbol{q}_n^T \end{pmatrix} = \boldsymbol{Q} \boldsymbol{Q}^T$$

Definition. The orthogonal projector onto C(Q), $Q \in \mathbb{R}^{m \times n}$ with orthonormal column vectors is $P = QQ^T$

• Given $u \in \mathbb{R}^m$ and $Q = (q_1 \dots q_n) \in \mathbb{R}^{m \times n}$ with orthonormal columns

Definition. The complementary orthogonal projector to $P = QQ^T$ is I - P, where $Q \in \mathbb{R}^{m \times n}$ is a matrix with orthonormal columns.

• The complementary orthogonal projector projects a vector onto the left null space, $N(\boldsymbol{Q}^T)$

- Consider the linear system Ax = b with $A \in \mathbb{R}^{m \times n}$, $x \in \mathbb{R}^n$, $b \in \mathbb{R}^m$. Orthogonal projectors and knowledge of the four fundamental matrix subspaces allows us to succintly express whether there exist no solutions, a single solution of an infinite number of solutions:
 - Consider the factorization QR = A, the orthogonal projector $P = QQ^T$, and the complementary orthogonal projector I P
 - If $||(I P)b|| \neq 0$, then b has a component outside the column space of A, and Ax = b has no solution
 - $\quad \mathsf{lf} \, \|(\boldsymbol{I}-\boldsymbol{P})\boldsymbol{b}\| \,{=}\, 0 \mathsf{, then } \, \boldsymbol{b} \,{\in}\, C(\boldsymbol{Q}) \,{=}\, C(\boldsymbol{A}) \mathsf{ and the system has at least one solution}$
 - If $N(A) = \{0\}$ (null space only contains the zero vector, i.e., null space of dimension 0) the system has a unique solution
 - If dim N(A) = n r > 0, then a vector $y \in N(A)$ in the null space is written as

$$\boldsymbol{y} = c_1 \boldsymbol{z}_1 + \ldots + c_{n-r} \boldsymbol{z}_{n-r}$$

and if x is a solution of Ax = b, so is x + y, since

$$A(x + y) = Ax + c_1Az_1 + ... + c_{n-r}Az_{n-r} = b + 0 + ... + 0 = b$$

The linear system has an (n-r)-parameter family of solutions