

- New concepts:
 - Orthonormal vector set
 - Transforming a basis set into an orthonormal set by Gram-Schmidt
 - QR factorization of a matrix

Definition. The Dirac delta symbol δ_{ij} is defined as

$$\delta_{ij} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

Definition. A set of vectors $\{\mathbf{u}_1, \dots, \mathbf{u}_n\}$ is said to be *orthonormal* if

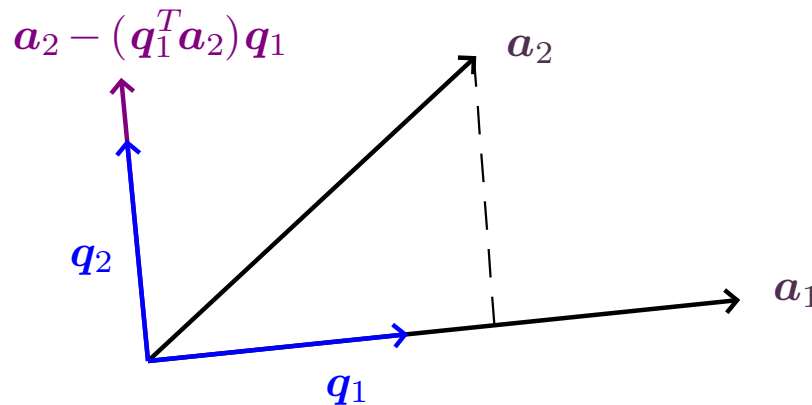
$$\mathbf{u}_i^T \mathbf{u}_j = \delta_{ij}$$

- The column vectors of the identity matrix are orthonormal

$$\mathbf{I} = (\mathbf{e}_1 \quad \dots \quad \mathbf{e}_m)$$

$$\mathbf{e}_i^T \mathbf{e}_j = \delta_{ij}$$

- An arbitrary vector set can be transformed into an orthonormal set by the Gram-Schmidt algorithm
- Idea:
 - Start with an arbitrary direction \mathbf{a}_1
 - Divide by its norm to obtain a unit-norm vector $\mathbf{q}_1 = \mathbf{a}_1 / \|\mathbf{a}_1\|$
 - Choose another direction \mathbf{a}_2
 - Subtract off its component along previous direction(s) $\mathbf{a}_2 - (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1$
 - Divide by norm $\mathbf{q}_2 = (\mathbf{a}_2 - (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1) / \|\mathbf{a}_2 - (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1\|$
 - Repeat the above



- Consider $\mathbf{A} \in \mathbb{R}^{m \times n}$ with linearly independent columns. By linear combinations of the columns of \mathbf{A} a set of orthonormal vectors $\mathbf{q}_1, \dots, \mathbf{q}_n$ will be obtained. This can be expressed as a matrix product

$$\mathbf{A} = (\mathbf{a}_1 \ \mathbf{a}_2 \ \dots \ \mathbf{a}_n) = (\mathbf{q}_1 \ \mathbf{q}_2 \ \dots \ \mathbf{q}_n) \begin{pmatrix} r_{11} & r_{12} & r_{13} & \dots & r_{1n} \\ 0 & r_{22} & r_{23} & \dots & r_{2n} \\ 0 & 0 & r_{33} & \dots & r_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \dots & r_{mn} \end{pmatrix} = \mathbf{Q} \mathbf{R}$$

with $\mathbf{Q} \in \mathbb{R}^{m \times n}$, $\mathbf{R} \in \mathbb{R}^{n \times n}$. The matrix \mathbf{R} is upper-triangular (also referred to as right-triangular) since to find vector \mathbf{q}_1 only vector \mathbf{a}_1 is used, to find vector \mathbf{q}_2 only vectors $\mathbf{a}_1, \mathbf{a}_2$ are used

- The above is equivalent to the system

$$\begin{cases} \mathbf{a}_1 = r_{11} \mathbf{q}_1 \\ \mathbf{a}_2 = r_{12} \mathbf{q}_1 + r_{22} \mathbf{q}_2 \\ \vdots \\ \mathbf{a}_n = r_{1n} \mathbf{q}_1 + r_{2n} \mathbf{q}_2 + \dots + r_{nn} \mathbf{q}_n \end{cases}$$

- The system can be solved to find R, Q by:

1. Imposing $\|q_1\| = 1 \Rightarrow r_{11} = \|a_1\|, q_1 = a_1 / r_{11}$

2. Computing projections of a_2, \dots, a_n along q_1

$$r_{12} = q_1^T a_2, \dots, r_{1n} = q_1^T a_n$$

3. Subtracting components along q_1 from a_2, \dots, a_n

$$\begin{cases} a_2 - r_{12}q_1 = r_{22}q_2 \\ \vdots \\ a_n - r_{1n}q_1 = r_{2n}q_2 + \dots + r_{nn}q_n \end{cases}$$

4. The above steps reduced the size of the system by 1. Repeating the steps completes the solution. The overall process is known as the Gram-Schmidt algorithm

Algorithm (Gram-Schmidt)

Given m vectors $\mathbf{a}_1, \dots, \mathbf{a}_m$

Initialize $\mathbf{q}_1 = \mathbf{a}_1, \dots, \mathbf{q}_m = \mathbf{a}_m, \mathbf{R} = \mathbf{I}$

for $i = 1$ to m

$r_{ii} = (\mathbf{q}_i^T \mathbf{q}_i)^{1/2}; \mathbf{q}_i = \mathbf{q}_i / r_{ii}$

 for $j = i+1$ to m

$r_{ij} = \mathbf{q}_i^T \mathbf{a}_j; \mathbf{q}_j = \mathbf{q}_j - r_{ij} \mathbf{q}_i$

 end

end

return \mathbf{Q}, \mathbf{R}

- For $A \in \mathbb{R}^{m \times n}$ with linearly independent columns, the Gram-Schmidt algorithm furnishes a factorization

$$QR = A$$

with $Q \in \mathbb{R}^{m \times n}$ with orthonormal columns and $R \in \mathbb{R}^{n \times n}$ an upper triangular matrix.

- Since the column vectors within Q were obtained through linear combinations of the column vectors of A we have

$$C(A) = C(Q)$$