



Overview

- Types of numerical approximation and their coding
- Array operations



- *Numerical methods* constructs approximation sequences $\{y_n\}_{n \in \mathbb{N}}$ to converge to the solution of a mathematical problem $y = P(x)$, $\lim_{n \rightarrow \infty} y_n = y$.
- *Numerical analysis* studies the convergence behavior: conditions for convergence, order and rate of convergence.
- *Computation theory* constructs algorithms within some model of computation and studies the behavior of these algorithms, in particular the computational effort required for each step of the algorithm



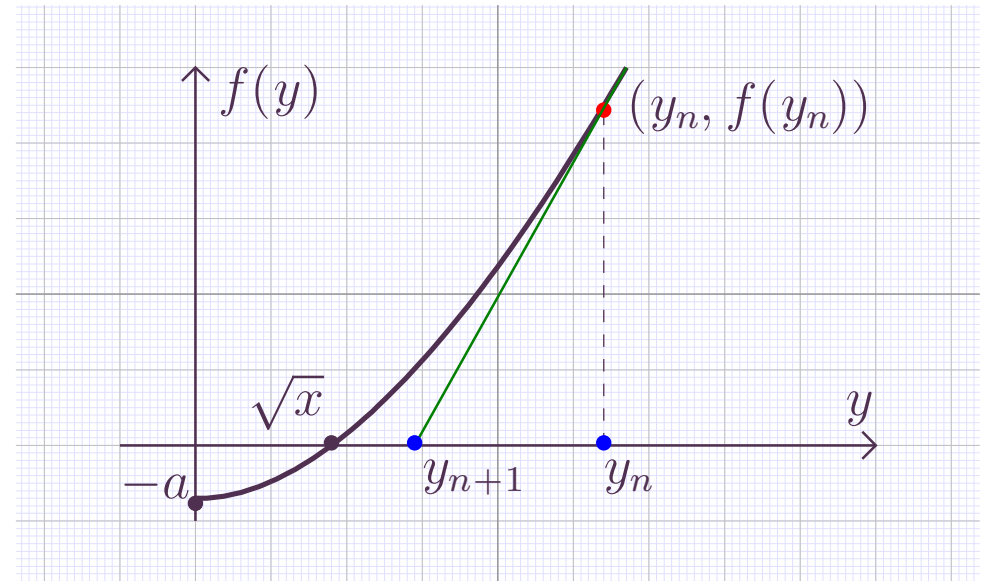
$$y_1 = 1, y_{n+1} = \frac{1}{2} \left(y_n + \frac{x}{y_n} \right),$$

$$\lim_{n \rightarrow \infty} y_n = \sqrt{x} = P(x).$$

$$f(y) = R(x, y) = x - y^2, r_n = R(x, y_n)$$

$$L_n(y) = f'(y_n)(y - y_n) + f(y_n)$$

$$L_n(y_{n+1}) = 0 \Rightarrow y_{n+1} = \frac{1}{2} \left(y_n + \frac{a}{y_n} \right)$$



$$y_1 = 1, y_{n+1} = \frac{1}{2} \left(y_n + \frac{a}{y_n} \right)$$

Suppose $y_n = \sqrt{x}(1 + \delta_n)$, signifying that y_n is " δ_n -close" to \sqrt{x} . Then, from $y_{n+1} - y_n = \frac{1}{2}(x/y_n - y_n)$ obtain

$$y_{n+1} - y_n = \frac{1}{2} \left[\frac{x}{\sqrt{x}(1 + \delta_n)} - \sqrt{x}(1 + \delta_n) \right] = \frac{\sqrt{x}}{2} \left[\frac{1}{1 + \delta_n} - 1 - \delta_n \right] \Rightarrow$$

$$y_{n+1} - y_n = \frac{\sqrt{x}}{2} [(1 - \delta_n + \delta_n^2 - \delta_n^3 + \dots) - 1 - \delta_n] = \delta_n \sqrt{x} \frac{2 - \delta_n}{2(1 - \delta_n)} \leq \delta_n \sqrt{x}.$$

For $\forall \varepsilon > 0$ choose N_ε such that $|\delta_{N_\varepsilon}| < \varepsilon / \sqrt{x}$ in which case $|y_{n+1} - y_n| < \varepsilon$, hence $\{y_n\}_{n \in \mathbb{N}}$ is a Cauchy sequence in \mathbb{R} , and converges.



- Newton's method for square root extraction: $f(y) = a - y^2 = 0$

$$y_1 = 1, y_{n+1} = \frac{1}{2} \left(y_n + \frac{a}{y_n} \right)$$

- At each iteration carry out 1 addition and two multiplications. Computational effort is $\mathcal{O}(2n)$ FLOPs (floating point operations)

- Newton's method for finding zeros of f , $f(y) = 0$

$$y_{n+1} = y_n - \frac{f(y_n)}{f'(y_n)}.$$

- At each iteration carry out 1 evaluation of f and 1 evaluation of f' . Computational effort is $\mathcal{O}(n)$ f -evals, and $\mathcal{O}(n)$ f' -evals.



- Additive corrections

$$\frac{\pi}{4} = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \frac{1}{9} - \dots,$$

$$L_n = \sum_{k=0}^n \frac{(-1)^k}{2k+1}, L_n = L_{n-1} + \frac{(-1)^n}{2n+1} \rightarrow \frac{\pi}{4}.$$

- Multiplicative corrections

$$S_n = \left(\frac{2}{1} \cdot \frac{2}{3}\right) \cdot \left(\frac{4}{3} \cdot \frac{4}{5}\right) \cdot \left(\frac{6}{5} \cdot \frac{6}{7}\right) \dots,$$

$$S_n = \prod_{k=1}^n \frac{4k^2}{4k^2-1} = S_{n-1} \cdot \frac{4n^2}{4n^2-1}, S_n \rightarrow \frac{\pi}{2}.$$



- Continued fractions

$$\pi + 3 = 6 + \frac{1^2}{6 + \frac{3^2}{6 + \frac{5^2}{6 + \ddots}}},$$

$$F_n = b_0 + \prod_{k=1}^n \frac{a_k}{b_k} = b_0 + \frac{a_1}{b_1 + \frac{a_2}{b_2 + \frac{a_3}{b_3 + \ddots}}},$$

$$y_n = 0, y_{n-1} = \frac{a_{n-1}}{b_{n-1} + y_n}, F_n = b_0 + y_1.$$



Definition. *The sum of matrices $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{m \times n}$*

$$\mathbf{A} = [a_{i,j}], \mathbf{B} = [b_{i,j}]$$

is the matrix $\mathbf{C} = \mathbf{A} + \mathbf{B}$ with components

$$\mathbf{C} = [c_{i,j}], c_{i,j} = a_{i,j} + b_{i,j}$$

Definition. *The scalar multiplication of matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ by $\alpha \in \mathbb{R}$ is $\mathbf{B} = \alpha \mathbf{A}$*

$$\mathbf{A} = [a_{i,j}], \mathbf{B} = [b_{i,j}] = [\alpha a_{i,j}]$$



Definition. Consider matrices $\mathbf{A} = [\mathbf{a}_1 \ \dots \ \mathbf{a}_n] \in \mathbb{R}^{m \times n}$, and $\mathbf{X} = [\mathbf{x}_1 \ \dots \ \mathbf{x}_p] \in \mathbb{R}^{n \times p}$. The **matrix product** $\mathbf{B} = \mathbf{A}\mathbf{X}$ is a matrix $\mathbf{B} = [\mathbf{b}_1 \ \dots \ \mathbf{b}_p] \in \mathbb{R}^{m \times p}$ with column vectors given by the matrix vector products

$$\mathbf{b}_k = \mathbf{A}\mathbf{x}_k, \text{ for } k = 1, 2, \dots, p.$$

- A matrix-matrix product is simply a set of matrix-vector products, and hence expresses multiple linear combinations in a concise way.
- The dimensions of the matrices must be compatible, the number of rows of \mathbf{X} must equal the number of columns of \mathbf{A} .
- A matrix-vector product is a special case of a matrix-matrix product when $p = 1$.
- We often write $\mathbf{B} = \mathbf{A}\mathbf{X}$ in terms of columns as

$$[\mathbf{b}_1 \ \dots \ \mathbf{b}_p] = \mathbf{A} [\mathbf{x}_1 \ \dots \ \mathbf{x}_p] = [\mathbf{A}\mathbf{x}_1 \ \dots \ \mathbf{A}\mathbf{x}_p]$$



Definition. Consider matrices $\mathbf{A} = [a_{i,j}] \in \mathbb{R}^{m \times n}$, and $\mathbf{X} = [x_{i,j}] \in \mathbb{R}^{n \times p}$. The *matrix product* $\mathbf{B} = \mathbf{A}\mathbf{X} = [b_{i,j}]$ is a matrix $\mathbf{B} \in \mathbb{R}^{m \times p}$ with components

$$b_{i,j} = a_{i,1}x_{1,j} + a_{i,2}x_{2,j} + \cdots + a_{i,n}x_{n,j} = \sum_{k=1}^n a_{i,k}b_{k,j}$$

$$\mathbf{A}\mathbf{X} = \begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & & a_{m,n} \end{bmatrix} \begin{bmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,n} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m,1} & x_{m,2} & & x_{m,n} \end{bmatrix}$$

$$b_{2,1} = a_{2,1}x_{1,1} + a_{2,2}x_{2,1} + \cdots + a_{2,n}x_{n,1}$$



- $A \in \mathbb{R}^{m \times n}$ contains n column vectors with m components each

$$A = [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \dots \quad \mathbf{a}_n]$$

- The transpose switches rows and columns

$$A^T = \begin{bmatrix} \mathbf{a}_1^T \\ \mathbf{a}_2^T \\ \vdots \\ \mathbf{a}_n^T \end{bmatrix} \in \mathbb{R}^{n \times m}$$

has n rows and m columns



- Matrix block addition

$$A = \begin{bmatrix} B & C \\ C & B \end{bmatrix}, D = \begin{bmatrix} E & F \\ F & E \end{bmatrix},$$

$$A + D = \begin{bmatrix} B & C \\ C & B \end{bmatrix} + \begin{bmatrix} E & F \\ F & E \end{bmatrix} = \begin{bmatrix} B + E & C + F \\ C + F & B + E \end{bmatrix}$$

- Matrix block multiplication

$$AD = \begin{bmatrix} B & C \\ C & B \end{bmatrix} \begin{bmatrix} E & F \\ F & E \end{bmatrix} = \begin{bmatrix} BE + CF & BF + CE \\ CE + BF & CF + BE \end{bmatrix}$$

- Matrix block transposition

$$M = \begin{bmatrix} U & V \\ X & Y \end{bmatrix}, M^T = \begin{bmatrix} U^T & X^T \\ V^T & Y^T \end{bmatrix}$$