



## Overview

Motivation: minimize interpolation error

$$f(t) - p_n(t) = \frac{f^{(n+1)}(\xi_t)}{(n+1)!} w(t), w(t) = \prod_{j=0}^n (t - x_j)$$

Here, the best possible behavior of  $w(t)$  is identified.

- Trigonometric expression of Chebyshev weight scalar product
- Chebyshev recurrence relation
- Roots and extrema of Chebyshev polynomials
- Minimal inf-norm property of Chebyshev polynomials
- Runge function on Chebyshev grid

- Chebyshev polynomials: obtained by orthonormalization of  $\{1, t, t^2, \dots\}$  w.r.t

$$(f, g) = \int_{-1}^1 \frac{f(t)g(t)}{\sqrt{1-t^2}} dt.$$

- The Gram-Schmidt process can be applied, but a quicker route is:

$$t = \cos \theta \Rightarrow dt = -\sin \theta d\theta = -\left(\sqrt{1-\cos^2\theta}\right)d\theta = -\left(\sqrt{1-t^2}\right)d\theta \Rightarrow$$

$$(f, g) = \int_0^\pi f(t(\theta))g(t(\theta)) d\theta = \int_0^\pi F(\theta)G(\theta) d\theta.$$

- Consider  $F(\theta) = \cos(j\theta)$ ,  $G(\theta) = \cos(k\theta)$  and compute

$$\int_0^\pi \cos(j\theta) \cos(k\theta) d\theta = c_j \delta_{jk}, c_0 = \pi, c_j = \frac{\pi}{2} \text{ for } j > 0$$



- Introduce notation  $T_n(t(\theta)) = \cos(n\theta)$  (*un-normalized Chebyshev polynomial*)
- Observe:  $T_0(t) = 1$ ,  $T_1(t) = \cos \theta = t$ ,

$$T_{n+1}(t(\theta)) + T_{n-1}(t(\theta)) = \cos[(n+1)\theta] + \cos[(n-1)\theta] = 2 \cos \theta \cos(n\theta)$$

- The above trigonometric identity leads to the recurrence relationship

$$T_{n+1}(t) = 2tT_n(t) + T_{n-1}$$

- Since  $T_0(t) = 1$ ,  $T_1(t) = t$ , recurrence relationship implies  $T_n(t)$  are polynomials

$$T_2(t) = 2t^2 - 1, T_3(t) = 4t^3 - 3t, T_4(t) = 8t^4 - 8t^2 + 1, \dots$$

- Unit-norm Chebyshev polynomials are  $T_n(t) / c_n$ ,  $c_0 = \pi$ ,  $c_j = \frac{\pi}{2}$ ,  $j > 1$

$$(T_m, T_n) = \int_{-1}^1 \frac{T_m(t)T_n(t)}{\sqrt{1-t^2}} dt = \int_0^\pi \cos(m\theta) \cos(n\theta) d\theta = c_n \delta_{mn}.$$

- Roots of Chebyshev polynomials:

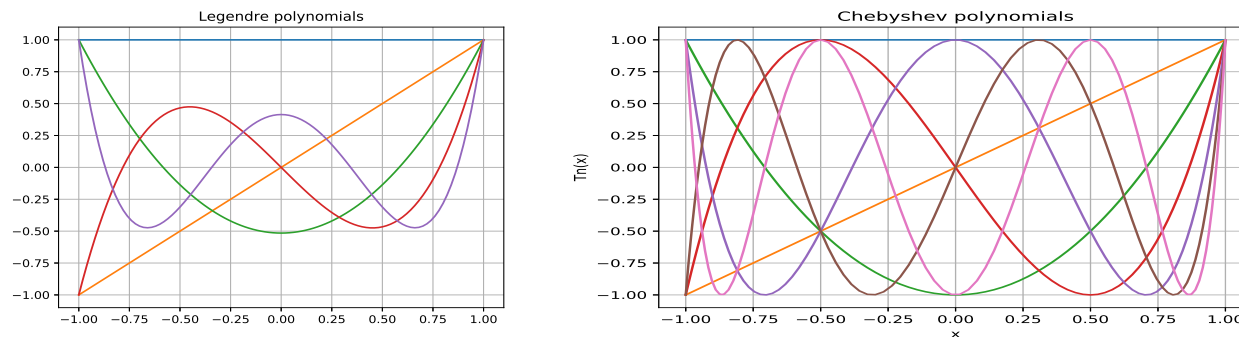
$$T_n(t(\theta)) = \cos(n\theta) = 0 \Rightarrow \theta_j = \frac{\pi(2j+1)}{2n}, z_j = \cos \theta_j, j = 0, 1, \dots, n-1$$

- Local extrema of Chebyshev polynomials:

$$T'_n(t) = -\frac{1}{\sin \varphi} \cdot \frac{d}{d\varphi} [T_n(t(\varphi))] = -\frac{1}{\sin \varphi} \cdot \frac{d \cos(n\varphi)}{d\varphi} = n \frac{\sin(n\varphi)}{\sin \varphi} = 0 \Rightarrow$$

$$\sin(n\varphi) = 0 \Rightarrow \varphi_j = \frac{j\pi}{n}, x_j = \cos \varphi_j = \cos \frac{j\pi}{n}, j = 1, 2, \dots, n-1$$

Include end point extrema:  $x_j = -\cos(j\pi/n), j = 0, 1, \dots, n$



**Figure 1.** Legendre and Chebyshev polynomials.



- Chebyshev polynomials and the behavior of  $w(t) = \prod_{j=0}^n (t - x_j)$
- Introduce inf-norm  $\|f\|_\infty = \max_{-1 \leq t \leq 1} |f(t)|$
- Monic form of Chebyshev polynomials:  $P_0(t) = 1$ ,  $P_n(t) = 2^{1-n} T_n(t)$

$$T_0(t) = 1, T_1(t) = t, T_2(t) = 2t^2 - 1, T_3(t) = 4t^3 - 3t, T_4(t) = 8t^4 - 8t^2 + 1, \dots$$

Coefficient of term of  $n^{\text{th}}$  degree in  $P_n(t)$  is one (*monic polynomial*) like  $w(t)$

$$\|P_0(t)\| = 1, \|P_n(t)\|_\infty = 2^{1-n}, n > 0$$

- Intuitively: Runge function overshoot of interpolant near interval endpoints

$$f(t) = \frac{1}{1 + (5t)^2}, f(t) - p_n(t) = \frac{f^{(n+1)}(\xi_t)}{(n+1)!} w(t), w(t) = \prod_{j=0}^n (t - x_j)$$

is not due to  $f^{(n+1)}(\xi_t)$  (very smooth), but to  $w(t)$ , i.e., choice of  $x_j$

- What monic polynomial has the smallest inf-norm? The Chebyshev polynomial.

**Theorem.**  $p: [-1, 1] \rightarrow \mathbb{R}$ , monic polynomial of degree  $n$  has a inf-norm lower bound

$$\|p\|_{\infty} = \max_{-1 \leq t \leq 1} |p(t)| \geq 2^{1-n}.$$

**Proof.** By contradiction, assume the monic polynomial  $p: [-1, 1] \rightarrow \mathbb{R}$  has  $\|p\|_{\infty} < 2^{1-n}$ . Construct a comparison with the Chebyshev polynomials by evaluating  $p$  at the extrema  $x_j = \cos(j\pi/n)$ ,

$$(-1)^j p(x_j) \leq |p(x_j)| < 2^{1-n} = (-1)^j P_n(x_j) = (-1)^j 2^{1-n} T_n(x_j).$$

Since the above states  $(-1)^j p(x_j) < (-1)^j P_n(x_j)$  deduce

$$(-1)^j [p(x_j) - P_n(x_j)] < 0, \text{ for } j = 0, 1, \dots, n \quad (1)$$

However,  $p, P_n$  both monic implies that  $p(x_j) - P_n(x_j)$  is a polynomial of degree  $n - 1$  that would change signs  $n$  times to satisfy (1), and thus have  $n$  roots contradicting the fundamental theorem of algebra.  $\square$

- For polynomial interpolant of degree  $n$  of  $f: [-1, 1] \rightarrow \mathbb{R}$  choose error term

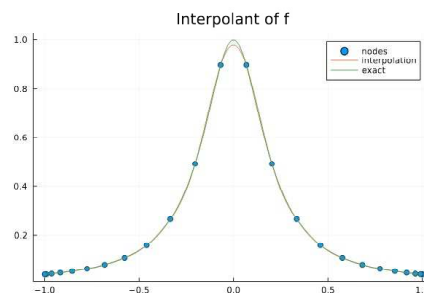
$$w(t) = \prod_{j=0}^n (t - z_j) = T_{n+1}(t), \quad z_j = \cos \theta_j, \quad \theta_j = \frac{\pi(2j+1)}{2(n+1)}, \quad j = 0, 1, \dots, n.$$

$$\mathcal{Z} = \{(z_j, f(z_j)), j = 0, 1, \dots, n\}$$

- Alternatively, roots of  $T'_n(t) = nU_{n-1}(t)$ ,  $U_{n-1}(t) = \sin(n\theta) / \sin \theta$  and  $\pm 1$

$$w(t) = \prod_{j=0}^n (t - x_j), \quad x_j = -\cos \varphi_j, \quad \varphi_j = \frac{j\pi}{n}, \quad j = 0, 1, \dots, n$$

$$\mathcal{D} = \{(x_j, f(x_j)), j = 0, 1, \dots, n\}$$



**Figure 2.** Chebyshev grid interpolant of degree 23

- *Numerical methods* suggested an orthogonal basis set  $\{T_0, T_1, \dots\}$
- *Numerical analysis* has furnished an optimal set of sample points  $x_j$  or  $z_j$
- Still to study: *computational complexity*
- Naïve approach:  $f(t) \cong p(t) = \sum_{j=0}^n c_j T_j(t)$ , apply interpolation conditions

$$y_j = f(x_j) = p(x_j) \Rightarrow [ T_0(\mathbf{x}) \quad T_1(\mathbf{x}) \quad \dots \quad T_n(\mathbf{x}) ] \mathbf{c} = \mathbf{y} \Leftrightarrow \mathbf{A} \mathbf{c} = \mathbf{y}$$

obtaining a linear system with a full matrix at computational cost  $\mathcal{O}(n^3/3)$

- Recall: polynomial interpolant is *unique*. Use Lagrange barycentric form

$$p(t) = \frac{\sum_{j=0}^n y_j \frac{w_j}{t - x_j}}{\sum_{j=0}^n \frac{w_j}{t - x_j}}$$

- When sample points are  $x_j = -\cos \varphi_j$ ,  $\varphi_j = \frac{j\pi}{n}$ ,  $j = 0, 1, \dots, n$ , weights are

$$w_j = (-1)^j, j = 1, \dots, m - 1, w_0 = 1/2, w_n = (-1)^n/2$$

favoring data set  $\mathcal{D} = \{(x_j, f(x_j))\}$  over  $\mathcal{Z} = \{(z_j, f(z_j))\}$ ,  $j = 0, 1, \dots, n$ .