

Overview

- Lanczos iteration
- Eigenvalue problem
- Orthogonal polynomials and Jacobi matrices
- Gauss Quadrature

- Consider $A \in \mathbb{R}^{m \times m}$ symmetric positive definite (as often arises in physics)
- The reduced Hessenberg matrix $H_n = Q_n^T A Q_n$ is symmetric, positive definite, tridiagonal.

$$\boldsymbol{H}_{n} = \boldsymbol{T}_{n} = \begin{pmatrix} \alpha_{1} & \beta_{1} & & & \\ \beta_{1} & \alpha_{2} & \beta_{2} & & \\ & \ddots & \ddots & \ddots & \\ & & \beta_{n-1} & \alpha_{n} \end{pmatrix}, \tilde{\boldsymbol{T}}_{n} = \begin{pmatrix} \alpha_{1} & \beta_{1} & & & \\ \beta_{1} & \alpha_{2} & \beta_{2} & & & \\ & \ddots & \ddots & \ddots & \ddots & \\ & & & \beta_{n-1} & \alpha_{n} & \\ & & & & \beta_{n} \end{pmatrix}$$

$$AQ_n = Q_{n+1}\tilde{T}_n \Rightarrow Aq_n = \beta_{n-1}q_{n-1} + \alpha_nq_n + \beta_nq_{n+1}$$

Algorithm Lanczos

Given:
$$\boldsymbol{b}, \boldsymbol{A}$$

$$\beta_0 = 0, \, \boldsymbol{q}_0 = \boldsymbol{0}, \, \boldsymbol{q}_1 = \boldsymbol{b} / \| \boldsymbol{b} \|$$
for $n = 1, 2, ...$

$$\boldsymbol{v} = \boldsymbol{A} \boldsymbol{q}_n, \, \alpha_n = \boldsymbol{q}_n^T \boldsymbol{v}$$

$$\boldsymbol{v} = \boldsymbol{v} - \beta_{n-1} \, \boldsymbol{q}_{n-1} - \alpha_n \, \boldsymbol{q}_n$$

$$\beta_n = \| \boldsymbol{v} \|$$

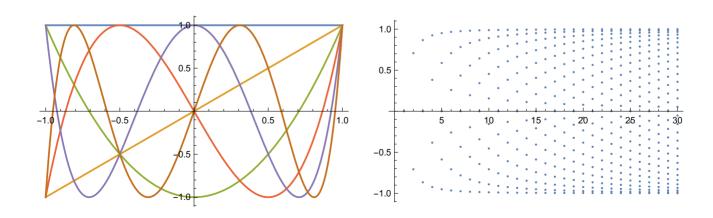
$$\boldsymbol{q}_{n+1} = \boldsymbol{v} / \beta_n$$

- Since Lanczos is a restriction of Arnoldi to s.p.d. matrices, all properties of Arnoldi localization of eigenvalues carry over, in particular solution $\min_{p^n \in P^n} \|p^n(A) b\|$ is characterisitic polynomial of $T_n = Q_n^* A Q_n$.
- Recall the definition of the Chebyshev polynomials for $x \in [-1, 1]$

$$T_m(x) = \cos(m\theta), x = \cos\theta$$

ullet Lanczos iteration converges rapidly if (scaled and centered) eigenvalue distribution of A differs substantially from that of the Chebyshev roots

$$x_{j} = \cos \theta_{j}, \theta_{j} = \frac{\pi}{m} \left(j - \frac{1}{2} \right), j = 1, ..., m$$



- Vectors $u, v \in \mathbb{R}^m$ are functions, $u, v : \{1, ..., m\} \to \mathbb{R}$. As $m \to \infty$, vectors u, v can be considered as samples from real functions $u, v : \mathbb{R} \to \mathbb{R}$
- $A \in \mathbb{R}^{m \times m}$ encodes a linear transformation between vector spaces, $A : \mathbb{R}^m \to \mathbb{R}^m$, b = Ax. As $m \to \infty$, A can be considered as an approximation (sample) of a linear operator between function spaces
- A Banach space $\mathcal B$ is a linear (vector) space endowed with a norm $\|\cdot\|:\mathcal B\to\mathbb R_+$
- A Hilbert space \mathcal{H} is a linear (vector) space endowed with a scalar product $(,): \mathcal{H} \times \mathcal{H} \to \mathbb{R}$
- The scalar product can be used to induce a 2-norm, $||u|| = (u, u)^{1/2}$
- Consider ${\cal H}$ to be the space of square-integrable functions defined on [-1,1], ${\cal H}=L^2[-1,1]$

$$(u,v) = \int_{-1}^{1} u(x) v(x) dx,$$

• Introduce operator ${\mathcal A}$ that when sampled leads to multiplication of a vector by a diagonal matrix

$$(\mathcal{A}[u])(x) = xu(x) = v(x)$$

- Consider the continuum generalization of a Krylov space
 - Replace $\boldsymbol{b} \in \mathbb{R}^m$ by the function $1 \in L^2[-2,2]$ with norm $\|1\| = (1,1)^{1/2} = \sqrt{2}$
 - Replace $\mathbf{A}\mathbf{b}$ by aplication of operator \mathcal{A} , e.g., $(\mathcal{A}[1])(x) = x \cdot 1$, $(\mathcal{A}[x])(x) = x \cdot x$, ...
 - Arrive at Krylov space span $\{1, x, x^2, ...\}$
 - Interpret sampling of operator relationship (A[u])(x) = xu(x) = v(x) at x_i as

$$Au = v, v_i = x_i u_i, A = diag(x_1, ..., x_m) = A^T$$

Construction of an orthogonal set of (Legendre) polynomials is identical to Lanczos iteration

Algorithm Lanczos: discrete and continuum

$$\begin{array}{ll} \beta_0 = 0, \, \boldsymbol{q}_0 = \boldsymbol{0}, \, \boldsymbol{q}_1 = \boldsymbol{b} / \| \boldsymbol{b} \| & \beta_0 = 0, \, q_0(x) = 0, \, q_1(x) = 1 / \sqrt{2} \\ \text{for } n = 1, 2, \dots & \\ \boldsymbol{v} = \boldsymbol{A} \, \boldsymbol{q}_n, \, \alpha_n = \boldsymbol{q}_n^T \boldsymbol{v} & v(x) = \mathcal{A}[q_n](x) = x \, q_n(x), \, \alpha_n = (q_n, v) \\ \boldsymbol{v} = \boldsymbol{v} - \beta_{n-1} \, \boldsymbol{q}_{n-1} - \alpha_n \, \boldsymbol{q}_n & v(x) = v(x) - \beta_{n-1} \, q_{n-1} - \alpha_n \, q_n \\ \beta_n = \| \boldsymbol{v} \| & \beta_n = \| \boldsymbol{v} \| \\ \boldsymbol{q}_{n+1} = \boldsymbol{v} / \beta_n & q_{n+1} = v / \beta_n \end{array}$$

- Properties of orthogonal polynomials can be obtained from linear algebra operations
- Define Krylov matrix as the sample of the continuum Krylov space at $x_i\!=\!i\,h$, $h\!=\!2/(m-1)$

$$\boldsymbol{x}^{k} = (x_{1}^{k} \dots x_{m}^{k})^{T}, \boldsymbol{K}_{n} = (1 \ \boldsymbol{x} \dots \boldsymbol{x}^{n-1})^{T}$$

• Tridiagonal matrices $m{T}_n = m{Q}_n^T m{A} m{Q}_n$ from Lanczos iteration are known as Jacobi matrices

$$(T_n)_{ij} = (q_i(x), x q_j(x)), Q_n = (q_1(x) \dots q_n(x))$$

• Exploit the relationship between discrete and continuum formulations by applying knowledge of the solution to polynomial approximation problem $\min_{p^n \in P^n} \|p^n(A)b\|$ for A a sample of A[u] = xu, and b a sample of 1. Conclude that

$$\operatorname{argmin}_{p^n \in P^n} ||p^n(x)|| = p_{T_n}, i.e.,$$

solution to the polynomial minimization problem is the characteristic polynomial of $m{T}_n$

- $\forall p \in P^n$, $p(x) = Cq_{n+1}(x) + Q_n(x) y$, $Q_n = (q_1(x) \dots q_n(x))$, $||p|| = (C^2 + ||y||^2)^{1/2}$
- ullet Conclude that roots of the orthogonal polynomial $q_{n+1}(x)$ are the eigenvalues of $oldsymbol{T}_n$

• Gauss quadrature for $f \in L^2[-1,1]$

$$\int_{-1}^{1} f(x) \, dx = \sum_{j=1}^{n} w_{j} f(x_{j})$$

$$\int_{-1}^{1} f(x) \, dx \cong \int_{-1}^{1} p_{n-1}(x) \, dx = \int_{-1}^{1} \sum_{j=1}^{n} \mathcal{L}_{i}(x) y_{i} \, dx = \sum_{j=1}^{n} \left[\int_{-1}^{1} \mathcal{L}_{i}(x) \, dx \right] y_{i}$$

$$w_{i} = \int_{-1}^{1} \mathcal{L}_{i}(x) \, dx = \int_{-1}^{1} \prod_{j=1}^{n} \frac{(x - x_{j})}{(x_{i} - x_{j})} \, dx$$

with nodes x_i given by roots of Legendre polynomials.

- ullet Find the orthogonal eigendecomposition of the Jacobi matrices $m{T}_n$, $m{T}_n = m{V}m{D}m{V}^T$
 - The nodes of the Gauss quadrature are eigenvalues of $m{T}_n$, $x_j = \lambda_j$
 - The weights of the Gauss quadrature are $w_j\!=\!2\,[(m{v}_j)_1]^2$, $m{V}\!=\!(m{v}_1\ ...\ m{v}_n\)$