

$$\sum_{j=0}^r a_j \mathcal{Q}^{(n+j)} = k \sum_{j=0}^r b_j f^{n+j}$$

$k = \text{time step size}$

$$\boxed{q' = f(t, q), \quad q(t)}$$

$$\mathcal{Q}^{(n+j)} \approx q(t^{n+j})$$

Euler  $t^{n+j} = (n+j)k$

$$Q^{n+1} = Q^n + k F^n$$

$$a_0 = -1 \quad a_1 = 1$$

$$p(z) = \sum_{j=0}^r a_j z^j \quad p(1) = 0$$

$$b(z) = \sum_{j=0}^r b_j z^j \quad b_0 = 1$$

Trapezoid

$$Q^{n+1} = Q^n + \frac{k}{2} (F^n + F^{n+1})$$

$$F^n \equiv f(t^n, Q^n)$$

$$p(z) = z - 1, \quad p(1) = 0$$

$$\sigma(z) = \frac{1}{2}z + \frac{1}{2}; \sigma$$

$$\tilde{\Delta} = \frac{1}{k} \sum_{j=0}^r a_j E^j \xrightarrow{(n \rightarrow \infty)} \frac{d}{dt}$$

$$\Delta = \sum_{j=0}^r b_j f(E^j) \xrightarrow{r \rightarrow \infty} f$$

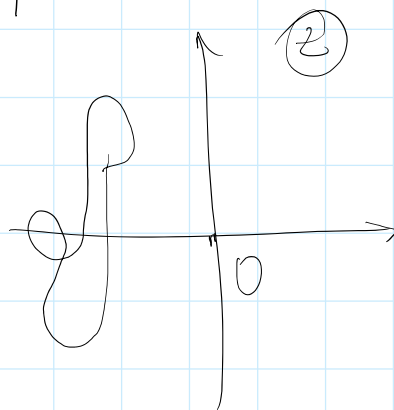
$E^j$

$$z^n = (\tilde{\Delta} - \Delta) z(t^n)$$

Consistency  $z(\theta) = \frac{f(e^{i\theta})}{\sigma(e^{i\theta})}$

$$f(1) = 0$$

$$f'(1) = \sigma(1)$$



$$\tilde{\pi}(z; z) = f(z) - z \sigma(z)$$

$$z = k\lambda$$

$$z' = f'(k\lambda) \rightarrow \text{Modal problem}$$

$$z' = \lambda z$$

$$\lambda \approx \frac{\partial f}{\partial z}$$

$$\lambda \equiv \frac{\partial f}{\partial z}$$

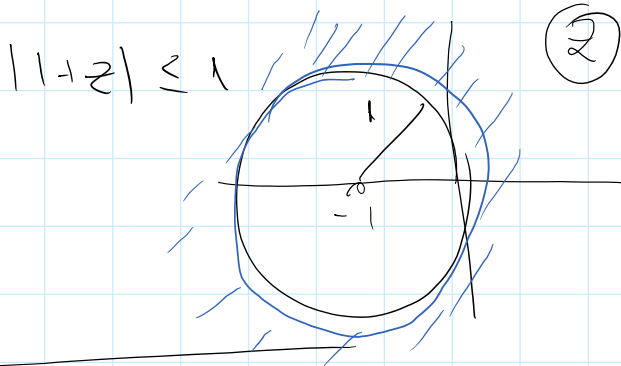
Euler

$$Q^{n+1} - Q^n = z Q^n$$

$$f(z) = z - 1 \quad \sigma(z) = 1$$

$$\begin{aligned} \pi(z; z) &= f(z) - z \sigma(z) \\ &= z - 1 - z = 0 \end{aligned}$$

$$\Rightarrow z = 1 + z$$



$$Q^{n+1} = Q^n + z Q^{n+1}$$

$$f(z) = z - 1$$

$$\sigma(z) = z$$

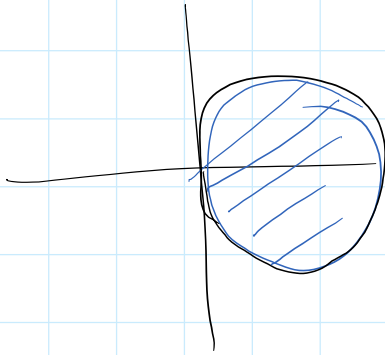
$$\pi(z; z) = z - 1 - z z = 0$$

$$z = \frac{1}{1-z}$$

$$|z| = \frac{1}{|1-z|} < 1$$

$$|1-z| = 1$$

$$|1-z| \geq 1 \quad z$$



## Trapezoid

$$p(z) = z - 1$$

$$q(z) = \frac{1}{2}(z+1)$$

$$\tilde{p}(z; 2) = z - 1 - \frac{z}{2}(z+1) = 0$$

$$\left(1 - \frac{z}{2}\right)z = 1 + \frac{z}{2} \Rightarrow$$

$$z = \frac{2+z}{2-z}$$

Boundary locus

$$z = e^{i\theta}$$

$$e^{i\theta} = \frac{2+z(\theta)}{2-z(\theta)}$$

$$z = \lambda_k$$

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$$\tilde{p}(z; 1) =$$

$$z - 1 - \frac{z}{2} - \frac{1}{2} = 0$$

$$\frac{z}{2} = \frac{3}{2} \Rightarrow$$

$$z = 3$$

$$z' = \lambda z$$

$$z = \lambda_k$$

$$z' = \lambda z + s(t)$$

$$2 - z(\theta) \quad |$$

$$2e^{i\theta} - e^{i\theta} z(\theta) = 2 + z(\theta)$$

$$z(\theta) [1 + e^{i\theta}] = 2(e^{i\theta} - 1)$$

$$z(\theta) = 2 \frac{e^{i\theta} - 1}{e^{i\theta} + 1}$$

$$0 \leq \theta < 2\pi$$

$$= \frac{\cos \frac{\theta}{2} - i \sin \frac{\theta}{2}}{\cos \frac{\theta}{2} + i \sin \frac{\theta}{2}}$$

$$z(\theta) = 2 \frac{\cos \theta - 1 + i \sin \theta}{\cos \theta + 1 + i \sin \theta}$$

$$= 2 \frac{-2 \sin^2 \frac{\theta}{2} + 2i \sin \frac{\theta}{2} \cos \frac{\theta}{2}}{2 \cos^2 \frac{\theta}{2} + 2i \sin \frac{\theta}{2} \cos \frac{\theta}{2}}$$

$$= 4 \tan \frac{\theta}{2} \cdot \frac{-\sin \frac{\theta}{2} + i \cos \frac{\theta}{2}}{\cos \frac{\theta}{2} + i \sin \frac{\theta}{2}}$$

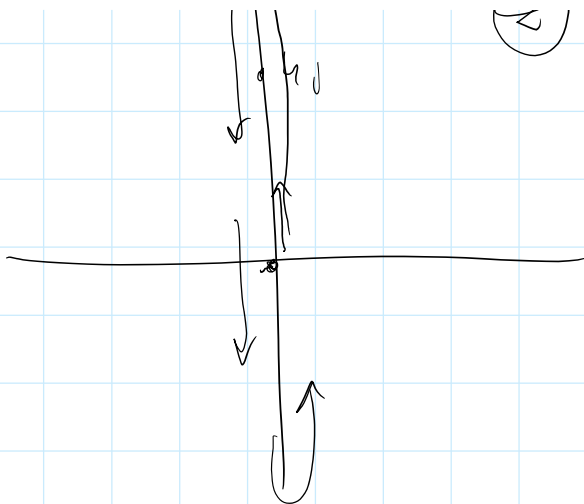
$$= 4 \tan \frac{\theta}{2} \frac{\cos \left( \frac{\pi}{2} + \frac{\theta}{2} \right) + i \sin \left( \frac{\pi}{2} + \frac{\theta}{2} \right)}{e^{i\theta/2}}$$

$$= 4 \tan \frac{\theta}{2} \frac{e^{i\pi/2} e^{i\theta/2}}{e^{i\theta/2}}$$

$$= 4i \tan \frac{\theta}{2}$$

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$$\theta = 0 \Rightarrow z(\theta) = 0$$

$$\theta = \frac{\pi}{2} \Rightarrow z\left(\frac{\pi}{2}\right) = 4i$$

$$\theta = \pi \Rightarrow z(\pi)$$

$$\tilde{\pi}(\mathcal{J}; z) = \underbrace{f(\mathcal{J}) - z \sigma(\mathcal{J})}_{z = \lambda k} \quad z = \lambda k$$

Model problem  $\begin{cases} q' = \lambda q \\ q(0) = q_0 \end{cases}$

Leap frog

$$Q^{n+1} = Q^{n-1} + z Q^n$$

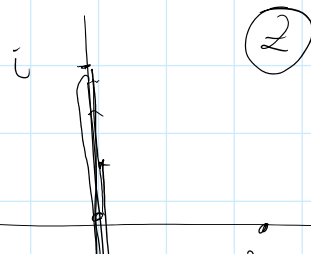
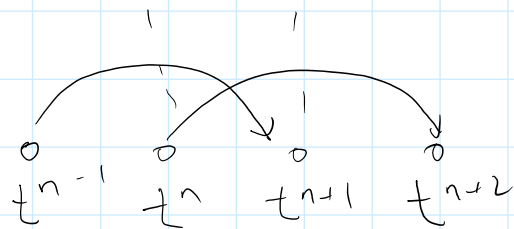
$$f(\mathcal{J}) = \mathcal{J}^2 - 1 \quad \sigma(\mathcal{J}) = \mathcal{J}$$

$$\mathcal{J} = e^{i\theta} \quad \tilde{\pi}(e^{i\theta}; z) = 0$$

$$z(\theta) = \frac{f(e^{i\theta})}{\sigma(e^{i\theta})}$$

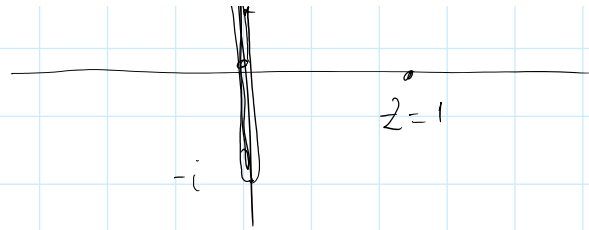
$$z(\theta) = \frac{e^{i\theta} - e^{-i\theta}}{2} = i \sin \theta$$

$$\tilde{\pi}(\mathcal{J}; 1) = \mathcal{J}^2 - 1 - \mathcal{J} = 0$$



$$\Pi(\lambda; 1) = \lambda^2 - 1 - \lambda = 0$$

$$\Rightarrow \lambda_{1,2} = \frac{1 \pm \sqrt{1+4}}{2}$$



$$Q_t + u Q_x = 0$$

advection equation

$$\frac{dQ}{dt} = \frac{u}{2h} A Q$$

$$Q(t) = \begin{pmatrix} Q_1(t) \\ Q_2(t) \\ \vdots \\ Q_m(t) \end{pmatrix}$$

$$Q_i(t) \cong Q(x_i, t) \quad x_i = ih$$

$$A = \begin{pmatrix} 0 & 1 & & & \\ -1 & & & & \\ & -1 & & & \\ & & -1 & & \\ & & & 0 & 1 \\ & & & & 0 \end{pmatrix} = \text{diag}(\underbrace{[-1 \ 0 \ \dots]}_m)$$

Adams-Bashforth of order 2

$$Q^{n+2} = Q^{n+1} + \frac{k}{2} (3Q^{n+1} - Q^n)$$

$$Q^{n+2} = Q^{n+1} + \frac{k}{2} (3f(Q^{n+1}) - f(Q^n))$$

Adams-Moulton of order 3

See Boundary Locus.nb on how to generate a famous plot in ODE numerical methods

