

Framework for solving a PDE

By variational principle:

$$(1) \quad Au = f$$

$$A: V \rightarrow W$$

A some operator

$a(u, v)$ associated bilinear form

Solution to (1) \Leftrightarrow solution of $a(u, v) = \langle f, v \rangle$
 \downarrow
 by variational calculus

$A: \mathbb{R}^m \rightarrow \mathbb{R}^m$ linear operator

$$a(u, v) = \langle Au, v \rangle$$

$$u = u_i e_i; \quad v = v_j e_j$$

$$\langle Au, v \rangle = \langle f, v \rangle \Leftrightarrow$$

$$Au = f \quad u, f \text{ vectors in } \mathbb{R}^m$$

Ex: $Au = f \quad a(u, v) = \langle Au, v \rangle = u^T A^T v$

Ex: (1) $-\nabla^2 u = f \Rightarrow a(u, v) = \langle \nabla u, \nabla v \rangle$

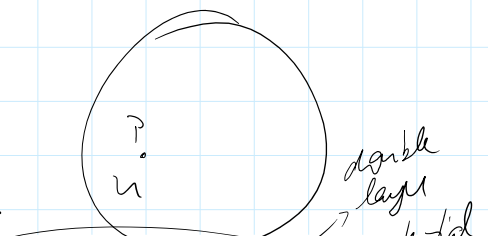
(2) $a(u, v) = \langle f, v \rangle \quad \forall v \in V$

(1) \Leftrightarrow (2)

Classical PDE theory 1920's, (Kellogg book)

$$(BVP) \left\{ \begin{array}{l} -\nabla^2 u = f \text{ in } \Omega \subset \mathbb{R}^3 \\ u|_{\partial\Omega} = g \end{array} \right.$$

Harmonic representation theorem



Harmonic representation theorem

General form

$$u_p = \frac{1}{4\pi} \int_{\Omega} \frac{f(\rho)}{r_{\rho}} d\rho$$

Volume potential

$$+ \frac{1}{4\pi} \int_{\partial\Omega} \frac{d}{dn} \left(\frac{1}{r_{\rho}} \right) g_1(r_{\rho}) d\rho$$

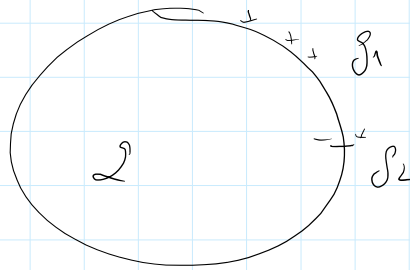
$$- \frac{1}{4\pi} \int_{\partial\Omega} \frac{g_2(r_{\rho})}{r_{\rho}} d\rho$$

single layer potential

u_i double layer potential

Ex: Electrostatics

$$-\nabla^2 V = \rho$$



Dirichlet B.C.

specify g_1, g_2 results

Neumann B.C.

specify g_2, g_1 results

Robin B.C.

specify linear combination

Summer Beach Reading List

- Morse & Feshbach
- Kellogg "Potential theory"
- Courant & Hilbert "Meth. of Math. Phys."
- Schwartz "Theory of Distributions"

$$Au = f \quad A \in \mathbb{R}^{n \times n}; \quad u, f \in \mathbb{R}^n$$

Lax - Milgram Theorem

$$Au = f \quad \xrightarrow[\text{calculus}]{\text{vari.}} \quad a(u, v) = \langle f, v \rangle \quad (2)$$

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(strong form) weak form

(2) has a solution for $\forall f$ if

a) a is bounded $|a(u, v)| \leq C \|u\| \|v\|$

C finite constant

b) a is coercive; $\exists c > 0$ s.t.

$$a(u, u) \geq c \|u\|^2$$

Ex: Linear system $Au = f$

$$a(u, u) = \langle Au, u \rangle = u^T A^T u \geq \underline{c} u^T u$$

Lax - Milgram generalizations

Lax - Milgram $a: H \times H \rightarrow \mathbb{R}$ H Hilbert

Babuška - Lax - Milgram $a: U \times V \rightarrow \mathbb{R}$ U, V Hilbert

Lions - Lax - Milgram $a: H \times V \rightarrow \mathbb{R}$ H Hilbert
 V normed

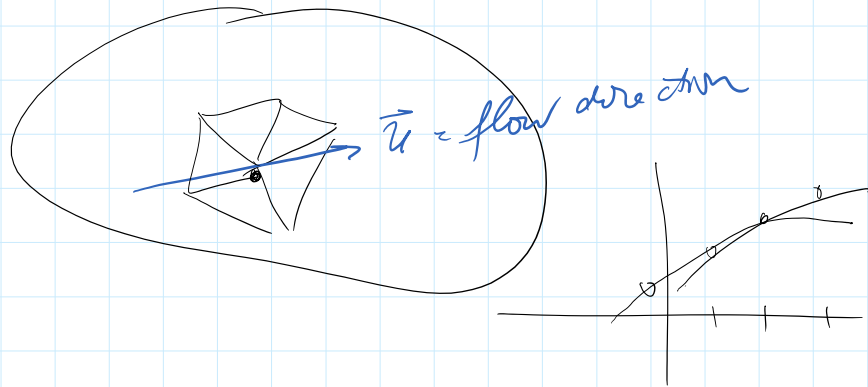
Lions: Theory for PDEs & FEMs (12, 14 volumes)

Textbook by Beatrice Riviere FEM Th. & Applications
(~ 300p).

HW3 = HW1 with FEM replacing FVM

FEM have difficulties with upwinding

(most common approach SUPG =
stream-wise upwind Petrov-Galerkin)



Incompressible flow: (Navier-Stokes eqs.)

$$\begin{cases} \vec{u}_t + (\vec{u} \cdot \nabla) \vec{u} = -\nabla p + \nu \nabla^2 \vec{u} \\ \nabla \cdot \vec{u} = 0 \end{cases}$$

is solved by operator splitting

(Projection method Chorin 1969)

J. Computational
Physics

Operator splitting stages

1) Advection

$$\vec{u}^n \rightarrow \vec{u}^* \quad \vec{u}_t + (\vec{u} \cdot \nabla) \vec{u} = -\nabla \chi$$

χ an approximation
of p

2) Diffusion

$$\vec{u}_t = \nu \nabla^2 \vec{u}$$

$$\vec{u}^* \rightarrow \vec{u}^{**}$$

$$3) \text{ Projection} \quad \vec{u}^{n+1} = \vec{u}^{**} + \nabla \phi$$

$$\nabla \cdot \vec{u}^{n+1} = 0 \Rightarrow$$

$$\nabla^2 \phi = -\nabla \cdot \vec{u}^{\text{ex}} \quad (\text{enforces } \nabla \cdot \vec{u} = 0)$$